Introduction to Quantum Computing

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LSSU Math 500

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- Grover's Algorithm
- Amplitude Amplification
- Optimality of Grover's Algorithm
- Derandomization and Amplitude Amplification
- Unknown Number of Solutions

Subsection 1

Grover's Algorithm

The Problem

- Grover's algorithm uses **amplitude amplification** to search an unstructured set of *N* elements.
- Suppose the property being searched for is given in terms of a Boolean function, or predicate,

$$P: \{0, \ldots, N-1\} \to \{0, 1\}.$$

- The goal of the problem is to find a solution.
- That is, identify an element x, such that

P(x) = 1.

The Classical Complexity

- As in Simon's problem and the Deutsch-Jozsa problem, the predicate *P* is viewed as an oracle or black box.
- So our focus is on the query complexity, the number of calls made to the oracle *P*.
- Given a black box that outputs P(x) upon input of x, the best classical approaches must, in the single solution case, inspect an average of $\frac{N}{2}$ values.
- That is, the classical approach requires an average of $\frac{N}{2}$ evaluations of the predicate P(x).

The Quantum Complexity

• Suppose, we are given a quantum black box U_P that sends

$$\sum_{x} c_{x} |x\rangle |0\rangle \to \sum_{x} c_{x} |x\rangle |P(x)\rangle.$$

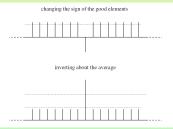
- Grover's algorithm finds a solution, in the single solution case, with only $O(\sqrt{N})$ calls to U_P .
- Grover's algorithm works by iteratively increasing the amplitudes c_x of those values x with P(x) = 1.
- As a result, a final measurement will return a value x of interest with high probability.
- For practical applications of Grover's algorithm, the predicate *P*:
 - Must be efficiently computable;
 - Should lack such structure as allows classical methods to gain advantage over the quantum algorithm.

Outline

• Grover's algorithm starts with an equal superposition of all *N* values of the search space,

$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum_{x} |x\rangle.$$

- It repeatedly performs the same sequence of transformations:
 - 1. Apply U_P to $|\psi\rangle$.
 - 2. Flip the sign of all basis vectors that represent a solution.
 - 3. Perform inversion about the average, a transformation that maps every amplitude $A \delta$ to $A + \delta$, where A is the average of the amplitudes.



Setup

- Without loss of generality, let $N = 2^n$ for some integer n.
- Let X be the state space generated by $\{|0\rangle, \ldots, |N-1\rangle\}$.
- Let U_P be a quantum black box that acts as

$$U_P: |x,a\rangle \rightarrow |x,P(x)\oplus a\rangle,$$

for all $x \in X$ and all single-qubit states $|a\rangle$.

• Denote the sets of good and bad values, respectively, by

$$G = \{x : P(x)\}$$
 and $B = \{x : \neg P(x)\}.$

• Let the number of good states be a small fraction of the total number of states, written

$$|G| \ll N$$
.

Setup (Cont'd)

- Consider the even superpositions:
 - Of all good states,

$$|\psi_G\rangle = \frac{1}{\sqrt{|G|}} \sum_{x \in G} |x\rangle;$$

• Of all bad states,

$$|\psi_B\rangle = \frac{1}{\sqrt{|B|}} \sum_{x \in B} |x\rangle.$$

• Then $|\psi\rangle = W|0\rangle$, an equal superposition of all N values, can be written as a superposition of $|\psi_G\rangle$ and $|\psi_B\rangle$

$$|\psi\rangle = \frac{1}{\sqrt{2^n}} \sum_{x=0}^{2^n-1} |x\rangle = g_0 |\psi_G\rangle + b_0 |\psi_B\rangle,$$

where
$$g_0 = \sqrt{\frac{|G|}{N}}$$
 and $b_0 = \sqrt{\frac{|B|}{N}}$.

Setup (Cont'd)

• The core of Grover's algorithm is the repeated application of a unitary transformation

$$Q:g_i|\psi_G\rangle + b_i|\psi_B\rangle \to g_{i+1}|\psi_G\rangle + b_{i+1}|\psi_B\rangle$$

that increases the amplitude g_i of good states (and decreases b_i).

- This is done until a maximal value is reached.
- After applying Q an appropriate number of times j, almost all amplitude will have shifted to good states, so that $|b_j| \ll |g_j|$.
- At this point, measurement will return an $x \in G$ with high probability.
- The exact number of times Q needs to be applied is on the order of \sqrt{N} and depends on both N and |G|.

Iteration Step: Changing the Sign of the Good Elements

- To change the sign in a superposition $\sum c_x |x\rangle$ of exactly those $|x\rangle$ such that $x \in G$, apply S_G^{π} .
- A sign change is simply a phase shift by $e^{i\pi} = -1$.
- We showed that

 $U_{\mathcal{P}}(|\psi\rangle \otimes \mathcal{H}|1\rangle) = (S_{\mathcal{G}}^{\pi}|\psi\rangle) \otimes \mathcal{H}|1\rangle.$

• Changing the sign of the good elements is accomplished by

 $U_P: (g_i|\psi_G\rangle + b_i|\psi_B\rangle) \otimes H|1\rangle \to (-g_i|\psi_G\rangle + b_i|\psi_B\rangle) \otimes H|1\rangle.$

• The number of gates needed to change the sign on the good elements does not depend on N, but rather on how many gates it takes to compute U_P .

Iteration Step: Inversion About the Average

- Let A be the average of the amplitudes of all basis vectors in the superposition.
- Inversion about the average sends

$$a|x\rangle \rightarrow (2A-a)|x\rangle.$$

• The transformation

$$\sum_{i=0}^{N-1} a_i |x_i\rangle \rightarrow \sum_{i=0}^{N-1} (2A - a_i) |x_i\rangle$$

is performed by the unitary matrix

$$D = \begin{pmatrix} \frac{2}{N} - 1 & \frac{2}{N} & \cdots & \frac{2}{N} \\ \frac{2}{N} & \frac{2}{N} - 1 & \cdots & \frac{2}{N} \\ \cdots & \cdots & \cdots & \cdots \\ \frac{2}{N} & \frac{2}{N} & \cdots & \frac{2}{N} \end{pmatrix}.$$

Iteration Step: Inversion About the Average (Cont'd)

- We implement D with $O(n) = O(\log_2(N))$ quantum gates.
- Following Grover, we define

$$D=-WS_0^{\pi}W,$$

where:

- W is the Walsh-Hadamard transform;
- S_0^{π} is the phase shift by π of the basis vector $|0\rangle$,

$$S_0^{\pi} = \begin{pmatrix} -1 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots \\ 0 & \cdots & \cdots & 0 \\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

• We now show that this $D = -WS_0^{\pi}W$ is the one we need.

Iteration Step: Inversion About the Average (Cont'd)

Let

$$R = \left(\begin{array}{cccc} 2 & 0 & \cdots & 0 \\ 0 & 0 & 0 & \cdots \\ 0 & \cdots & \cdots & 0 \\ 0 & \cdots & 0 & 0 \end{array}\right).$$

• We have
$$S_0^{\pi} = I - R$$
.

So we get

$$-WS_0^{\pi}W = W(R-I)W = WRW - I.$$

$$(WRW)_{ij} = W_{i0}R_{00}W_{0j} = \frac{2}{N}$$

Iteration Step: Inversion About the Average (Cont'd)

We got

$$-WS_0^{\pi}W$$
 and $(WRW)_{ij} = \frac{2}{N}$.

So we obtain

$$-WS_0^{\pi}W = WRW - I = D.$$

- We finally put together:
 - Inversion about the average;
 - Changing the sign of the good elements.
- This yields the iteration transformation

$$Q = -WS_0^{\pi}WS_G^{\pi}.$$

Number of Iterations: Intuition

- We examine the result of multiple application of the iteration step Q.
- The goal is to determine the optimal number of times to apply Q.
- We show that:
 - Q is a fixed rotation;
 - The amplitude g_i of good states varies periodically with the number of iterations.
- To find a solution with high probability, the number of iterations *i* must be chosen carefully.
- To determine the correct number of iterations to use, we describe the result of applying *Q* in terms of recurrence relations on *g_i* and *b_i*.

Number of Iterations: Formalism

• The iteration step $Q = DS_G^{\pi}$ transforms

$$g_i|\psi_G\rangle + b_i|\psi_B\rangle \rightarrow g_{i+1}|\psi_G\rangle + b_{i+1}|\psi_B\rangle.$$

First,

$$S_G^{\pi}:g_i|\psi_G\rangle+b_i|\psi_B\rangle\rightarrow -g_i|\psi_G\rangle+b_i|\psi_B\rangle.$$

• To compute the average amplitude, A_i, note that:

- The term $-g_i|\psi_G\rangle$ contributes |G| amplitudes $\frac{-g_i}{\sqrt{|G|}}$;
- The term $b_i |\psi_B
 angle$ contributes |B| amplitudes $\frac{b_i}{\sqrt{|B|}}$.
- Thus, altogether

$$A_i = \frac{\sqrt{|B|}b_i - \sqrt{|G|}g_i}{N}.$$

Number of Iterations: Inversion About the Average

• Next, we turn to inversion about the average transforms,

$$D: -g_i |\psi_G\rangle + b_i |\psi_B\rangle$$

$$\rightarrow \sum_{x \in G} \left(2A_i + \frac{g_i}{\sqrt{|G|}} \right) |x\rangle + \sum_{x \in B} \left(2A_i - \frac{b_i}{\sqrt{|B|}} \right) |x\rangle$$

$$= (2A_i \sqrt{|G|} + g_i) |\psi_G\rangle + (2A_i \sqrt{|B|} - b_i) |\psi_B\rangle$$

$$= g_{i+1} |\psi_G\rangle + b_{i+1} |\psi_B\rangle,$$

where

$$g_{i+1} = 2A_i\sqrt{|G|} + g_i,$$

 $b_{i+1} = 2A_i\sqrt{|B|} - b_i.$

Number of Iterations: Solving the Recurrence Relations

- Let t denote the probability that a random value in $\{0, \ldots, N-1\}$ satisfies P.
- Then we have

$$t = rac{|G|}{N}$$
 and $1 - t = rac{|B|}{N}$.

Now we get

• So, for the recurrence relations, we have:

$$g_{i+1} = 2A_i \sqrt{|G|} + g_i$$

= $2(\sqrt{t(1-t)}b_i - tg_i) + g_i$
= $(1-2t)g_i + 2\sqrt{t(1-t)}b_i$.

Number of Iterations: Solving the Recurrences (Cont'd)

Similarly,

$$b_{i+1} = 2A_i\sqrt{|B|} - b_i$$

= 2((1-t)b_i - \sqrt{t(1-t)}g_i) - b_i
= (1-2t)b_i - 2\sqrt{t(1-t)}g_i.

• We also have

$$g_0 = \sqrt{t}$$
 and $b_0 = \sqrt{1-t}$.

• We can verify that

$$g_i = \sin\left((2i+1)\theta\right), \quad b_i = \cos\left((2i+1)\theta\right)$$

is a solution to these equations with $\sin \theta = \sqrt{t} = \sqrt{\frac{|G|}{N}}$.

Number of Iterations: Computing the Optimum

- We are now ready to compute the optimum number of iterations of Q.
- We wish to find an element with the desired property P.
- This calls for maximizing the probability of measuring a good state.
- So we wish to choose *i*, such that

$$\sin((2i+1)\theta) \approx 1 \text{ or } (2i+1)\theta \approx \frac{\pi}{2}.$$

For |G| ≪ N, the angle θ becomes very small.
So √^{|G|}/_N = sin θ ≈ θ.

• Thus, g_i will be maximal for

$$(2i+1)\sqrt{\frac{|G|}{N}} \approx \frac{\pi}{2} \quad \Rightarrow \quad 2i+1 \approx \frac{\pi}{2}\sqrt{\frac{N}{|G|}}$$
$$\Rightarrow \quad i \approx \frac{\pi}{4}\sqrt{\frac{N}{|G|}} - \frac{1}{2}$$
$$\Rightarrow \quad i \approx \frac{\pi}{4}\sqrt{\frac{N}{|G|}}.$$

Number of Iterations: Computing the Optimum (Cont'd)

- Additional iteration will reduce the success probability.
- This situation is in contrast to many classical algorithms in which the greater the number of iterations the better the results.
- Using the equations for g_i and b_i :
 - For t = ¹/₄, the optimum number of iterations is 1.
 Indeed, we have

$$\sin \theta = \sqrt{t} = \frac{1}{2} \qquad \Rightarrow \qquad \theta = \frac{\pi}{6}; \\ g_i = \sin\left((2i+1)\frac{\pi}{6}\right) \qquad \Rightarrow \qquad i = 1.$$

• For $t = \frac{1}{2}$, no amount of iteration will improve the situation. Indeed, we have

$$\sin \theta = \sqrt{t} = \frac{\sqrt{2}}{2} \qquad \Rightarrow \qquad \theta = \frac{\pi}{4};$$

$$g_i = \sin\left((2i+1)\frac{\pi}{4}\right) \qquad \Rightarrow \qquad i = 0.$$

Revisiting the Geometric Interpretation

- Every step of the iteration process has been written as a linear combination of $|\psi_G\rangle$ and $|\psi_B\rangle$ with real coefficients.
- So Grover's algorithm can be viewed as acting in the real two-dimensional subspace spanned by |ψ_G⟩ and |ψ_B⟩.
- The algorithm simply shifts amplitude from $|\psi_B\rangle$ to $|\psi_G\rangle$.
- This picture leads to an elegant geometric interpretation of Grover's algorithm to be discussed shortly.
- First, we describe a generalization of Grover's algorithm, *amplitude amplification*, to which this geometric picture also applies.

Subsection 2

Amplitude Amplification

Generalizing Amplitude Amplification

• The first step of Grover's algorithm applies the iteration operator

$$Q = -WS_0^{\pi}WS_G^{\pi}$$

to the initial state $W|0\rangle$.

- *W* can be viewed as a trivial algorithm mapping $|0\rangle$ to all possible values.
- So it maps $|0\rangle$ to a solution with probability $\frac{|G|}{N}$.
- Suppose we have an algorithm U, such that $U|0\rangle$ gives an initial solution with a higher probability.
- We show that the previous analysis generalizes to any algorithm U, such that $U|0\rangle$ has some amplitude in the good states.
- Amplitude amplification generalizes Grover's algorithm by replacing the iteration operator $Q = -WS_0^{\pi}WS_G^{\pi}$ with

$$Q=-US_0^{\pi}U^{-1}S_G^{\pi}.$$

Normalized Projections

- Let G be the subspace spanned by {|x⟩ : x ∈ G}.
- Let *B* be the subspace spanned by {|*x*⟩ : *x* ∉ *G*}.
- Let $P_{\mathcal{G}}$ and $P_{\mathcal{B}}$ be the associated projection operators.
- Let $|\psi_G\rangle$ be the normalized projection of $|\psi\rangle$ onto the good subspace,

$$|\psi_G\rangle = \frac{1}{g_0} P_{\mathcal{G}} |\psi\rangle, \quad g_0 = |P_{\mathcal{G}} |\psi\rangle|$$

• Let $|\psi_B
angle$ be the normalized projection of $|\psi
angle$ onto the bad subspace,

$$|\psi_B\rangle = \frac{1}{b_0} P_B |\psi\rangle, \quad b_0 = |P_B |\psi\rangle|.$$

• Let $|\psi\rangle = U|0\rangle$ be written as

$$|\psi\rangle = g_0|\psi_G\rangle + b_0|\psi_B\rangle.$$

Measurement and Probabilities

- For U = W, we take $|\psi_G\rangle$, $|\psi_B\rangle$, g_0 and b_0 are as before.
- Here g_0 and b_0 are not determined by the number of solutions, but rather by the properties of U relative to the good states.
- The states $|\psi_G\rangle$ and $|\psi_B\rangle$ need not be equal superpositions of the good and bad states respectively, but g_0 and b_0 are still real.
- Again, we let

$$t = g_0^2$$
, with $1 - t = b_0^2$,

where t should be thought of as the probability that measurement of the superposition $U|0\rangle$ yields a state that satisfies predicate P.

• The operator U can be viewed as a reversible algorithm that maps $|0\rangle$ to a set of solutions in G with a probability $t = |g_0|^2$.

The Effect of Applying Q

• To understand the effect of $Q = -US_0^{\pi}U^{-1}S_G^{\pi}$, recall that $S_0^{\pi}|\varphi\rangle$ can be written as

$$S_0^{\pi}|\varphi\rangle = |\varphi\rangle - 2\langle 0|\varphi\rangle|0\rangle.$$

• For an arbitrary state $|\psi\rangle$,

$$US_0^{\pi} U^{-1} |\psi\rangle = U(U^{-1} |\psi\rangle - 2\langle 0|U^{-1} |\psi\rangle |0\rangle)$$

= $|\psi\rangle - 2\langle 0|U^{-1} |\psi\rangle U|0\rangle$
= $|\psi\rangle - 2\overline{\langle \psi|U|0\rangle} U|0\rangle.$

The Effect of Applying Q (Cont'd)

• We got

$$US_0^{\pi}U^{-1}|\psi\rangle = |\psi\rangle - 2\overline{\langle\psi|U|0\rangle}U|0\rangle.$$

Now recall that

$$S_G^{\pi}|\psi_G\rangle = -|\psi_G\rangle$$
 and $S_G^{\pi}|\psi_B\rangle = |\psi_B\rangle$.

• So we get

$$\begin{aligned} Q|\psi_G\rangle &= -US_0^{\pi}U^{-1}S_G^{\pi}|\psi_G\rangle \\ &= US_0^{\pi}U^{-1}|\psi_G\rangle \\ &= |\psi_G\rangle - 2\overline{g_0}U|0\rangle \\ &= |\psi_G\rangle - 2\overline{g_0}g_0|\psi_G\rangle - 2\overline{g_0}b_0|\psi_B\rangle \\ &= (1-2t)|\psi_G\rangle - 2\sqrt{t(1-t)}|\psi_B\rangle \end{aligned}$$

The Effect of Applying Q (Cont'd)

• Similarly, we have

$$\begin{aligned} Q|\psi_B\rangle &= -US_0^{\pi}U^{-1}S_G^{\pi}|\psi_B\rangle \\ &= -US_0^{\pi}U^{-1}|\psi_B\rangle \\ &= -|\psi_B\rangle + 2\overline{\langle\psi_B|U|0\rangle}U|0\rangle \\ &= -|\psi_B\rangle + 2\overline{b_0}U|0\rangle \\ &= -|\psi_B\rangle + 2\overline{b_0}g_0|\psi_G\rangle + 2\overline{b_0}b_0|\psi_B\rangle \\ &= -|\psi_B\rangle + 2(1-t)\frac{g_0}{b_0}|\psi_G\rangle + 2(1-t)|\psi_B\rangle \\ &= (1-2t)|\psi_B\rangle + 2\sqrt{t(1-t)}|\psi_G\rangle. \end{aligned}$$

The Effect of Applying Q (Cont'd)

We obtained

$$\begin{array}{lll} Q|\psi_G\rangle &=& (1-2t)|\psi_G\rangle - 2\sqrt{t(1-t)}|\psi_B\rangle;\\ Q|\psi_B\rangle &=& (1-2t)|\psi_B\rangle + 2\sqrt{t(1-t)}|\psi_G\rangle. \end{array}$$

• An arbitrary real superposition of $|\psi_G\rangle$ and $|\psi_B\rangle$ is transformed by Q as follows:

$$Q(g_i|\psi_G\rangle + b_i|\psi_B\rangle) = (g_i(1-2t) + 2b_i\sqrt{t(1-t)})|\psi_G\rangle + (b_i(1-2t) - 2g_i\sqrt{t(1-t)})|\psi_B\rangle.$$

• This leads to the same recurrence relation as in the previous section,

$$g_{i+1} = (1-2t)g_i + 2\sqrt{t(1-t)}b_i;$$

$$b_{i+1} = (1-2t)b_i - 2\sqrt{t(1-t)}g_i.$$

It has the solution

$$g_i = \sin((2i+1)\theta), \quad b_i = \cos((2i+1)\theta), \quad \sin\theta = \sqrt{t} = g_0.$$

Number of Iterations

• Thus, for small g₀, the amplitude g_i will be maximal after

$$i \approx \frac{\pi}{4} \frac{1}{g_0}$$

iterations.

- If the algorithm U succeeds with probability t, then simple classical repetition of U requires an average of $\frac{1}{t}$ iterations to find a solution.
- Amplitude amplification speeds up this process so that it takes only $O\left(\sqrt{\frac{1}{t}}\right)$ tries to find a solution.

Comments

- If U has no amplitude in the good states, g_0 will be zero and amplitude amplification will have no effect.
- Recall that no amount of iteration in Grover's algorithm improves the probability if $t = \frac{1}{2}$.
- Similarly, if g_0 is large, amplitude amplification cannot improve the situation.
- For this reason, amplitude amplification applied to an algorithm *U* that is the result of amplitude amplification does not improve the results.

Geometry of Amplitude Amplification

- Let $|\psi_G\rangle$, $|\psi_B\rangle$ and $Q = -US_0^{\pi}U^{-1}S_G^{\pi}$ be as defined before.
- We show that the entire discussion of amplitude amplification, and Grover's algorithm in particular, reduces to a simple geometric argument about rotations in the two-dimensional real subspace generated by {|\u03c6_G}, |\u03c6_B}.

Geometry (Cont'd)

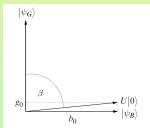
• By the definition of $|\psi_G\rangle$ and $|\psi_B\rangle$, the initial state

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U|0\rangle = g_0|\psi_G\rangle + b_0|\psi_B\rangle
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has real amplitudes g_0 and b_0 .

- So it is in the two-dimensional real plane spanned by $\{|\psi_G\rangle, |\psi_B\rangle\}$.
- The smaller the success probability t, the closer $U|0\rangle$ is to $|\psi_B\rangle$.
- Let β be the angle between $U|0\rangle$ and $|\psi_G\rangle$.
- The angle β depends only on the probability t = g₀² that the initial state U|0⟩, if measured, gives a solution

$$\cos\left(\beta\right) = \langle \psi_G | U | 0 \rangle = g_0.$$



Geometry (The Goal)

- The rest of this section explains how each iteration of Grover's algorithm rotates the state by a fixed angle in the direction of the desired state.
- To maximize the amplitude in the good states, we iterate until the state is close to |ψ_G⟩.
- From the simple geometry of the situation, we can determine:
 - The optimal number of iterations;
 - The probability that the run succeeds.

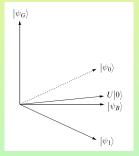
Geometry (Reflection)

• Amplitude amplification, and Grover's algorithm as the special case when U = W, consists of repeated applications of

$$Q = -US_0^{\pi} U^{-1} S_G^{\pi}.$$

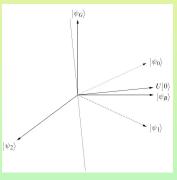
- Recall that the transformation S^π_G can be viewed as a reflection about the hyperplane perpendicular to |ψ_G⟩.
- In the plane spanned by $\{|\psi_G\rangle, |\psi_B\rangle\}$, this hyperplane reduces to the one-dimensional space spanned by $|\psi_B\rangle$.
- In the figure S_G^{π} maps an arbitrary state $|\psi_0\rangle$ in the $\{|\psi_G\rangle, |\psi_B\rangle\}$ subspace to

$$|\psi_1\rangle = S_G^{\pi} |\psi_0\rangle.$$



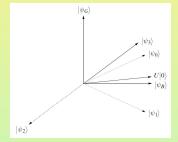
Geometry (Another Reflection)

- Similarly, the transformation S_0^{π} is a reflection about the hyperplane orthogonal to $|0\rangle$.
- Since $US_0^{\pi}U^{-1}$ differs from S_0^{π} by a change of basis, it is a reflection about the hyperplane orthogonal to $U|0\rangle$.
- The effect of this transformation on $|\psi_1
 angle$ is shown below:



Geometry (The Negative Sign)

- The final negative sign reverses the direction of the state vector.
- Strictly speaking, this negative sign is unnecessary, since it does nothing to the quantum state.
- It is a global phase change, so it is physically irrelevant.



 However, since we are drawing our pictures in the plane, not in projective space, the negative sign makes it easier to see what is going on.

Geometry (Rotation)

- The concatenation of two reflections is a rotation of twice the angle between the axes of the two reflections.
- The two axes of reflection in this case are perpendicular to $U|0\rangle$ and $|\psi_G\rangle$ respectively.
- So the angle between the axes of reflection is $-\beta$ where $\cos\beta = g_0$.
- The two reflections perform a rotation by -2β .
- The final negation amounts to a rotation by π .
- Thus, each step Q performs a rotation by $\pi 2\beta$.

Geometry (Conclusion)

- Each step Q performs a rotation by $\pi 2\beta$.
- Let $\theta = \frac{\pi}{2} \beta$, the angle between $U|0\rangle$ and $|\psi_B\rangle$.
- So $\sin \theta = g_0$.
- Each iteration of Q rotates the state by 2θ .
- So the angle after *i* steps is $(2i + 1)\theta$.
- As before, the amplitude in the good states after *i* steps is given by

$$g_i = \sin\left((2i+1)\theta\right).$$

• We solve for the optimal number of iterations just as we did before.

Subsection 3

Optimality of Grover's Algorithm

Optimality

- Even before Grover discovered his algorithm, researchers had proved a lower bound on the query complexity of any possible quantum algorithm for exhaustive search.
- It turns out that no quantum algorithm can use fewer than $\Omega(\sqrt{N})$ calls to the predicate U_P .
- Thus, Grover's algorithm is optimal.

Speedup

- The exponential size of the quantum state space gives naive hope that quantum computers could provide an exponential speedup for all computations.
- A less naive guess would be that quantum computers can provide exponential speedup for any computation that:
 - Can be parallelized;
 - Requires only a single answer output.
- The optimality of Grover's algorithm shows that even that hope is too optimistic.
- Exhaustive search is easily parallelized and requires a single answer.
- But quantum computers can provide only a relatively small speedup.

Role of S_x^{π}

- We showed how S_x^{π} can be computed from U_P .
- We use S_x^{π} as the interface to the oracle.
- We do not lose any generality in doing so.
 - The process of computing S_x^{π} from U_P is reversible;
 - So any algorithm using S_x^{π} could be rewritten in terms of U_P and vice versa.
- The oracle U_P provides us with the only way to access any information about the element x we are searching for.

Role of S_x^{π} (Cont'd)

- It follows that an arbitrary quantum search algorithm can be viewed as an algorithm that alternates between:
 - Unitary transformations independent of x;
 - Calls to S_x^{π} .
- That is, any quantum search algorithm can be written as

$$|\psi_k^{\mathsf{X}}\rangle = U_k S_{\mathsf{X}}^{\pi} U_{k-1} S_{\mathsf{X}}^{\pi} \cdots U_1 S_{\mathsf{X}}^{\pi} U_0 |0\rangle,$$

where the U_i are unitary transformations that do not depend on x.

- The argument does not change if we allow the use of additional qubits.
- We simply use $I \otimes S_x^{\pi}$ instead of S_x^{π} .
- Moreover, as N is now larger, the algorithm will be less efficient.

Independence from x

- It is important to recognize that the algorithm must work no matter which x is the solution.
 - For any particular x, there are transformations that find x very quickly.
 - We want an algorithm that finds x quickly no matter what x is.
- Any search algorithm worth the name must return x with reasonable probability, for all possible values of x.
- We consider only quantum search algorithms that return x with at least probability $p = \frac{1}{2}$.
- It is easy for the reader to check that any value $0 results in a <math>O(\sqrt{N})$ bound, just with a different constant.
- We will show that if the state $|\psi_k^x\rangle$, obtained after k steps of the form $U_i S_x^{\pi}$, satisfies $|\langle x | \psi_k^x \rangle|^2 \ge \frac{1}{2}$, for all x, then k must be $\Omega(\sqrt{N})$.

Intuition Behind the Proof

- We require hat the algorithm work for any x.
- So, if the oracle interface is S_x^{π} , then the result of applying

 $U_k S_x^{\pi} U_{k-1} S_x^{\pi} \cdots U_1 S_x^{\pi} U_0 |0\rangle$

must be a state $|\psi_k^x\rangle$ sufficiently close to $|x\rangle$ so that x will be obtained upon measurement with high probability.

- Note that two elements of the standard basis |x⟩ and |y⟩ cannot be closer than a certain constant.
- So the final states of the algorithm for different S_x^{π} and S_y^{π} must be sufficiently far apart.

Intuition Behind the Proof (Cont'd)

- Now the U_i are all the same.
- It follows that any difference in the result arises from calls to S_{χ}^{π} .
- The algorithms all start with the same state $U_0|0\rangle$.
- We want to obtain a bound on k, the number of calls to the oracle interface S^π_x.
- For this we need to bound from above the amount each step increases the distance between |ψ^x_i⟩ and |ψ^y_i⟩.

Intuition Behind the Proof (Cont'd)

- In other words, we want to bound from above the amount this distance can increase by:
 - Applying $U_i S_x^{\pi}$ to $|\psi_{i-1}^{\times}\rangle$;
 - Applying $U_i S_y^{\pi}$ to $|\psi_{i-1}^y\rangle$.
- Let |ψ_i⟩ be the state obtained by applying U₀ up through U_i without any intervening calls to S^π_x.
- To obtain the bound, we compare both $|\psi_i^{\mathsf{x}}\rangle$ and $|\psi_i^{\mathsf{y}}\rangle$ with $|\psi_i\rangle$.
- We first give the details of how to use inequalities based on these ideas to prove that $\Omega(\sqrt{N})$ calls to the oracle are required.
- Then we give detailed proofs of each of the inequalities.

Phase-Adjustment

- The proof considers the relation between three classes of quantum states:
 - The desired result $|x\rangle$;
 - The state of the computation $|\psi_k^{\mathsf{x}}\rangle$ after k steps;
 - The state $|\psi_k\rangle = U_k U_{k-1} \cdots U_1 U_0 |0\rangle$ obtained by performing the sequence of transformations U_i without consulting the oracle.
- The analysis simplifies if we sometimes consider, instead of |x), a phase-adjusted version of |x),

$$|x'_k\rangle = e^{\mathbf{i}\theta^{\times}_k}|x\rangle, \quad e^{\mathbf{i}\theta^{\times}_k} = \frac{\langle x|\psi^{\times}_k\rangle}{|\langle x|\psi^{\times}_k\rangle|}.$$

Phase-Adjustment (Cont'd)

- $e^{i\theta_k^x}$ is chosen so that $\langle x_k'|\psi_k^x\rangle$ is positive real for all k.
- Indeed, we have

$$\begin{aligned} \mathsf{x}_{k}'|\psi_{k}^{\mathsf{x}}\rangle &= e^{-\boldsymbol{i}\theta_{k}^{\mathsf{x}}}\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle \\ &= \frac{\overline{\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle}}{|\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle|}\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle \\ &= \frac{|\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle|^{2}}{|\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle|} \\ &= |\langle \mathbf{x}|\psi_{k}^{\mathsf{x}}\rangle| \ge 0. \end{aligned}$$

- $|x'_k\rangle$ differs from $|x\rangle$ only in a phase.
- So we have

$$\begin{split} \langle \boldsymbol{x} | \boldsymbol{\psi}_{k}^{\boldsymbol{x}} \rangle |^{2} \geq \frac{1}{2} & \Rightarrow \quad |\langle \boldsymbol{x}_{k}' | \boldsymbol{\psi}_{k}^{\boldsymbol{x}} \rangle |^{2} \geq \frac{1}{2} \\ & \Rightarrow \quad \langle \boldsymbol{x}_{k}' | \boldsymbol{\psi}_{k}^{\boldsymbol{x}} \rangle \geq \frac{1}{\sqrt{2}}. \end{split}$$

Distances Between States

• We consider the distances between certain pairs of these states:

$$d_{kx} = ||\psi_k^x\rangle - |\psi_k\rangle|, \quad a_{kx} = ||\psi_k^x\rangle - |x_k'\rangle|, \quad c_{kx} = ||x_k'\rangle - |\psi_k\rangle|.$$

• We establish bounds involving the average of these distances squared,

$$D_k = \frac{1}{N} \sum_{x} d_{kx}^2, \quad A_k = \frac{1}{N} \sum_{x} a_{kx}^2, \quad C_k = \frac{1}{N} \sum_{x} c_{kx}^2.$$

- The reason for considering the sum, or equivalently the average, is that the algorithm must efficiently find x for all possible x.
- The proof relies on three inequalities involving D_k , A_k , and C_k .
- Before proving the inequalities, we describe them and show how they imply a lower bound on the number of calls to the oracle.

The Three Inequalities

- The first inequality bounds from above A_k, the average squared distance between the state |ψ_k^x⟩ obtained after k steps, and |x_k'⟩. We will show that in order to obtain a success probability of |⟨x|ψ_k^x⟩|² ≥ 1/2, we must have A_k ≤ 2 √2.
- The second inequality bounds from below C_k, the sum of the squared distances between the vector |ψ_k⟩ and all basis vectors |j⟩.
 We see that, as long as N ≥ 4, C_k ≥ 1.
- The third inequality bounds the growth of D_k, the average squared distance between |ψ^x_k⟩ and |ψ_k⟩ as k increases, D_k ≤ ^{4k²}/_N.
- The three quantities d_{kx} , a_{kx} and c_{kx} are related as follows:

$$d_{kx} = ||\psi_k^{\mathsf{x}}\rangle - |\psi_k\rangle| = ||\psi_k^{\mathsf{x}}\rangle - e^{\mathbf{i}\theta_x^k}|x\rangle + e^{\mathbf{i}\theta_x^k}|x\rangle - |\psi_k\rangle| \ge a_{kx} - c_{kx}.$$

Averages and Number of Iterations

• Using the Cauchy-Schwarz inequality, we obtain

$$D_{k} = \frac{1}{N} \sum_{x} d_{kx}^{2}$$

$$\geq \frac{1}{N} (\sum_{x} a_{kx}^{2} - 2 \sum_{x} a_{kx} c_{kx} + \sum_{x} c_{kx}^{2})$$

$$\geq \frac{1}{N} \sum_{x} a_{kx}^{2} - \frac{2}{N} \sqrt{(\sum_{x} a_{kx}^{2})(\sum_{x} c_{kx}^{2})} + \frac{1}{N} \sum_{x} c_{kx}^{2}$$

$$\geq A_{k} - 2\sqrt{A_{k}C_{k}} + C_{k}.$$

• We make use of this inequality, together with

$$A_k \leq 2 - \sqrt{2}, \quad C_k \geq 1, \quad D_k \leq \frac{4k^2}{N}.$$

• We bound $\frac{4k^2}{N}$ from below by a constant.

Averages and Number of Iterations (Cont'd)

We use

$$D_k \ge A_k - 2\sqrt{A_k C_k} + C_k$$

together with $A_k \le 2 - \sqrt{2}$, $C_k \ge 1$ (for $N \ge 4$) and $D_k \le \frac{4k^2}{N}$. • We obtain

$$\frac{4k^2}{N} \geq D_k$$

$$\geq A_k - 2\sqrt{A_k C_k} + C_k$$

$$= (\sqrt{C_k} - \sqrt{A_k})^2$$

$$\geq (1 - \sqrt{2 - \sqrt{2}})^2. \quad (1 \geq 2 - \sqrt{2} \geq A_k)$$

• Thus, for $N \ge 4$, and taking $q = 1 - \sqrt{2 - \sqrt{2}}$, at least

$$k \ge \frac{q}{2}\sqrt{N}$$

iterations are required for success probability $|\langle x | \psi_k^x \rangle|^2 \ge \frac{1}{2}$, for all x.

The Inequality for A_k

- By assumption, $|\langle \psi_k^x | x \rangle|^2 \ge \frac{1}{2}$.
- By the choice of phase e^{iθ^x/_k} relating |x⟩ and |x'_k⟩, ⟨ψ^x_k|x'_k⟩ ≥ 1/√2.
 So
 a²_{t→1} = ||ψ^x_k⟩ |x'_k⟩|²

$$\begin{aligned} & \sum_{kx}^{2} &= ||\psi_{k}^{x}\rangle - |x_{k}'\rangle|^{2} \\ &= ||\psi_{k}^{x}\rangle|^{2} - 2\langle x_{k}'|\psi_{k}^{x}\rangle + ||x_{k}'\rangle|^{2} \\ &\leq 2 - \sqrt{2}. \end{aligned}$$

• From this it follows that

$$A_k = \frac{1}{N} \sum_{x} a_{kx}^2 \le 2 - \sqrt{2}.$$

The Inequality for C_k

С

• The terms c_{kx}^2 can be bounded as follows:

$$\begin{aligned} & \stackrel{2}{k_{x}} &= ||x_{k}'\rangle - |\psi_{k}\rangle|^{2} \\ &= |e^{i\theta_{k}^{x}}|x\rangle - |\psi_{k}\rangle|^{2} \\ &= ||\psi_{k}\rangle|^{2} - \overline{e^{i\theta_{k}^{x}}\langle\psi_{k}|x\rangle} - e^{i\theta_{k}^{x}}\langle\psi_{k}|x\rangle + ||x\rangle|^{2} \\ &= 2 - 2\operatorname{Re}(e^{i\theta_{k}^{x}}\langle\psi_{k}|x\rangle) \\ &\geq 2 - 2|\langle x|\psi_{k}\rangle|. \end{aligned}$$

The Inequality for C_k (Cont'd)

• We can now bound the average of these terms:

$$C_{k} = \frac{1}{N} \sum_{x} c_{kx}^{2}$$

$$\geq 2 - \frac{2}{N} \sum_{x} |\langle x | \psi_{k} \rangle|$$

$$\geq 2 - \frac{2}{\sqrt{N}} \sqrt{\sum_{x} |x| \psi_{k} \rangle|^{2}} \quad \text{(Cauchy-Schwarz)}$$

$$= 2 - \frac{2}{\sqrt{N}}.$$

$$(|\psi_{k}\rangle \text{ a unit vector and } \{|x\}\} \text{ a basis)}$$

- Thus, $C_k \ge 1$, as long as $N \ge 4$.
- Note that this argument made no assumption about $|\psi_k\rangle$.
- So this bound holds for any quantum state $|\psi
 angle$,

$$\frac{1}{N}\sum_{x}||x\rangle - |\psi\rangle|^2 \ge 2 - \frac{2}{\sqrt{N}}.$$

The Inequality for D_k

d

- First, we bound how much the distance between $|\psi_k^{\rm X}\rangle$ and $|\psi_k\rangle$ can increase each step.
- Consider the following relation between d_{kx} and $d_{k+1,x}$,

$$\begin{aligned} ||\psi_{k+1,x}^{x} &= ||\psi_{k+1}^{x}\rangle - |\psi_{k+1}\rangle| \\ &= |U_{k+1}S_{x}^{\pi}|\psi_{k}^{x}\rangle - U_{k+1}|\psi_{k}\rangle| \\ &= |S_{x}^{\pi}|\psi_{k}^{x}\rangle - |\psi_{k}\rangle| \\ &= |S_{x}^{\pi}(|\psi_{k}^{x}\rangle - |\psi_{k}\rangle) + (S_{x}^{\pi} - I)|\psi_{k}\rangle| \\ &\leq |S_{x}^{\pi}(|\psi_{k}^{x}\rangle - |\psi_{k}\rangle)| + |(S_{x}^{\pi} - I)|\psi_{k}\rangle| \\ &= d_{kx} + 2|\langle x|\psi_{k}\rangle|. \end{aligned}$$

This inequality shows that with each step the distance between |ψ^x_k⟩ and |ψ_k⟩ can increase by at most 2|⟨x|ψ_k⟩|.

• Using this bound, we prove by induction that $D_k = \frac{1}{N} \sum_{x} d_{kx}^2 \leq \frac{4k^2}{N}$.

The Inequality for D_k (Cont'd)

• **Base Case**: Let *k* = 0.

Then, for all x,

$$|\psi_0^{\times}\rangle = U_0|0\rangle = |\psi_0\rangle.$$

So $d_{0\times} = 0$. Therefore, $D_0 = 0$.

• Induction Step:

$$D_{k+1} = \frac{1}{N} \sum_{x} d_{k+1,x}^{2}$$

$$\leq \frac{1}{N} \sum_{x} (d_{kx} + 2|\langle x|\psi_{k}\rangle|)^{2}$$

$$= \frac{1}{N} \sum_{x} d_{kx}^{2} + \frac{4}{N} \sum_{x} |\langle x|\psi_{k}\rangle|^{2} + \frac{4}{N} \sum_{x} d_{kx} |\langle x|\psi_{k}\rangle|$$

$$= D_{k} + \frac{4}{N} + \frac{4}{N} \sum_{x} d_{kx} |\langle x|\psi_{k}\rangle|.$$

The Inequality for D_k (Cont'd)

We obtained

$$D_{k+1} \leq D_k + \frac{4}{N} + \frac{4}{N} \sum_{x} d_{kx} |\langle x | \psi_k \rangle|.$$

• The Cauchy-Schwarz inequality gives

$$\frac{1}{N} \sum_{x} d_{kx} |\langle x | \psi_{k} \rangle| \leq \frac{1}{N} \sqrt{(\sum_{x} d_{kx}^{2})(\sum_{x} |\langle x | \psi_{k} \rangle|^{2})} \\ = \sqrt{\frac{D_{k}}{N}}.$$

• By the induction assumption $D_k \leq \frac{4k^2}{N}$.

So we have

$$D_{k+1} \leq D_k + \frac{4}{N} + 4\sqrt{\frac{D_k}{N}} \leq \frac{4(k+1)^2}{N}.$$

Subsection 4

Derandomization and Amplitude Amplification

Suggested Approached for Derandomization

- Unlike Shor's algorithm, Grover's algorithm is not inherently probabilistic.
- With a little cleverness, Grover's algorithm can be modified in such a way that:
 - It is guaranteed to find a solution;
 - It still preserves the quadratic speedup.
- More generally, amplitude amplification can be derandomized.
- Brassard, Høyer and Tapp suggest two approaches:
 - In the first, each iteration rotates by an angle that is slightly smaller than the one used previously;
 - The second changes only the last step to a smaller rotation.

Approach 1: Modifying Each Step (Idea)

- Suppose the angle θ in Grover's algorithm (or amplitude amplification) happened to be such that $\frac{\pi}{4\theta} \frac{1}{2}$ is an integer.
- In this case, after $i = \frac{\pi}{4\theta} \frac{1}{2}$ iterations, the amplitude g_i would be 1.
- Accordingly, the algorithm would output a solution with certainty.
- Recall that θ satisfies sin $\theta = \sqrt{t} = g_0$.
- We hope to derandomize amplitude amplification for algorithm U with success probability g_0 .
- We modify U to obtain an algorithm U' with success probability $g'_0 < g_0$ such that, for θ' satisfying $\sin \theta' = g'_0$, the quantity

$$\frac{\pi}{4\theta'} - \frac{1}{2}$$

is an integer.

Approach 1: Modifying Each Step

- Intuitively, it seems as though it should not be hard to modify an algorithm *U* so that it is less successful.
- We must make sure that we can compute U' efficiently from U.
- The trick is to allow the use of an additional qubit *b*.
- We assume given an algorithm U with success probability g₀ acting on an n-qubit register |s>.
- Let B be the single-qubit transformation

$$B = \sqrt{1 - \frac{g_0'}{g_0}} |0\rangle + \sqrt{\frac{g_0'}{g_0}} |1\rangle.$$

• We define U' to be the transformation

$$U \otimes B$$

on an
$$(n+1)$$
-qubit register $|s\rangle|b\rangle$.

Approach 1: Modifying Each Step (Cont'd)

- Let G' be the set of basis states $|x\rangle \otimes |b\rangle$, with $|x\rangle \in G$, $|b\rangle = |1\rangle$.
- It may be checked that the initial success probability

 $|P_{G'}U'|0\rangle|=g_0'.$

- Perform amplitude amplification on an (n + 1)-qubit state, with:
 - U' for U;
 - $S_{G'}^{\pi}$ for S_{G}^{π} ;
 - Iteration operator $Q' = -U'S_0^{\pi}(U')^{-1}S_{G'}^{\pi}$.
- It succeeds with certainty after $i = \frac{\pi}{4\theta'} \frac{1}{2}$ steps.
- This modified algorithm obtains a solution with certainty, using $O(\sqrt{\frac{1}{t}})$ calls to the oracle, at the cost of a single additional qubit.

Approach 2: Modifying Only the Last Step

- This approach results in a solution in $O(\sqrt{\frac{1}{t}})$ time with certainty without the need for an additional qubit.
- The idea is to modify S_G^{π} and S_0^{π} in the last step so that exactly the desired final state is obtained.
- We begin by analyzing general properties of transformations of the form

$$Q(\phi,\tau) = -US_0^{\phi}U^{-1}S_G^{\tau},$$

where ϕ and τ are arbitrary angles and

$$S_X^{\phi}|x\rangle = \begin{cases} e^{i\phi}|x\rangle, & \text{if } |x\rangle \in X, \\ |x\rangle, & \text{if } |x\rangle \notin X. \end{cases}$$

• We have showed how to implement S_X^{ϕ} efficiently.

Approach 2: An Equation

• First, we show that, for any quantum state $|v\rangle$,

$$US_0^{\phi}U^{-1}|v\rangle = |v\rangle - (1 - e^{\mathbf{j}\phi})\overline{\langle v|U|0\rangle}U|0\rangle.$$

Write

$$|v\rangle = \sum_{i=1}^{N-1} \overline{\langle v|U|i\rangle} U|i\rangle + \overline{\langle v|U|0\rangle} U|0\rangle.$$

Then

$$US_{0}^{\phi}U^{-1}|v\rangle = US_{0}^{\phi}\left(\sum_{i=1}^{N-1}\overline{\langle v|U|i\rangle}|i\rangle + \overline{\langle v|U|0\rangle}|0\rangle\right)$$
$$= U\left(\sum_{i=1}^{N-1}\overline{\langle v|U|i\rangle}|i\rangle + \overline{\langle v|Ue^{i\phi}|0\rangle}|0\rangle\right)$$
$$= \sum_{i=1}^{N-1}\overline{\langle v|U|i\rangle}U|i\rangle + e^{i\phi}\overline{\langle v|U|0\rangle}U|0\rangle$$
$$= |v\rangle - (1 - e^{i\phi})\overline{\langle v|U|0\rangle}U|0\rangle.$$

Approach 2: An Equation (Cont'd)

• Using this result, we now can see the effect of

$$Q(\phi,\tau) = US_0^{\phi} U^{-1} S_G^{\tau}$$

on any superposition $|v\rangle = g|v_G\rangle + b|v_B\rangle$ in the subspace spanned by $|v_G\rangle$ and $|v_B\rangle$.

We have

$$Q(\phi,\tau)|v\rangle = g(-e^{i\tau}|v_G\rangle + e^{i\phi}(1-e^{i\phi})\overline{\langle v_G|U|0\rangle}U|0\rangle) +b(-|v_B\rangle + (1-e^{i\phi})\overline{\langle v_B|U|0\rangle}U|0\rangle).$$

• After $s = \lfloor \frac{\pi}{4\theta} - \frac{1}{2} \rfloor$ iterations of amplitude amplification, we have the state

$$|\psi_{s}\rangle = \sin\left((2s+1)\theta\right)|\psi_{G}\rangle + \cos\left((2s+1)\theta\right)|\psi_{B}\rangle,$$

where $\sin \theta = \sqrt{t} = g_0$.

Approach 2: An Equation (Cont'd)

• Applying $Q(\phi, \tau)$ to the state $|\psi_G
angle$, we obtain

$$Q(\phi,\tau)|\psi_{G}\rangle = -US_{0}^{\phi}U^{-1}S_{G}^{\tau}|\psi_{G}\rangle$$

$$= -US_{0}^{\phi}U^{-1}(e^{i\tau}|\psi_{G}\rangle)$$

$$= -e^{i\tau}|\psi_{G}\rangle + (1 - e^{i\phi})\overline{\langle e^{i\tau}\psi_{G}|U|0\rangle}U|0\rangle$$

$$= -e^{i\tau}|\psi_{G}\rangle + e^{i\tau}(1 - e^{i\phi})\overline{\langle \psi_{G}|g_{0}\psi_{G} + b_{0}\psi_{B}\rangle}$$

$$(g_{0}\psi_{G} + b_{0}\psi_{B})$$

$$= e^{i\tau}((1 - e^{i\phi})g_{0}^{2} - 1)|\psi_{G}\rangle$$

$$+ e^{i\tau}(1 - e^{i\phi})g_{0}b_{0}|\psi_{B}\rangle).$$

• Similarly, applying $Q(\phi, \tau)$ to the state $|\psi_B\rangle$, we obtain

$$Q(\phi,\tau)|\psi_B\rangle = (1-e^{i\phi})b_0g_0|\psi_G\rangle + ((1-e^{i\phi})b_0^2-1)|\psi_B\rangle).$$

Approach 2: An Equation (Cont'd)

• So
$$Q(\phi,\tau)|\psi\rangle = g(\phi,\tau)|\psi_G\rangle + b(\phi,\tau)|\psi_B\rangle$$
, where

$$g(\phi,\tau) = \sin((2s+1)\theta)e^{i\tau}((1-e^{i\phi})g_0^2-1) + \cos((2s+1)\theta)(1-e^{i\phi})b_0g_0 b(\phi,\tau) = \sin((2s+1)\theta)e^{i\tau}(1-e^{i\phi})g_0b_0 + \cos((2s+1)\theta)((1-e^{i\phi})b_0^2-1).$$

• Our aim now is to show that there exist ϕ and au such that if

$$Q(\phi,\tau) = US_0^{\phi}U^{-1}S_G^{\tau}$$

is applied as a final step, a solution is obtained with certainty.

Approach 2: An Equation (Cont'd)

- To show that φ and τ can be chosen so that Q(φ, τ)|ψ⟩ has all of its amplitude in the good states, we want b(φ, τ) = 0.
- That is, we need

$$(\sin ((2s+1)\theta)e^{i\tau}(1-e^{i\phi})g_0b_0) + \cos ((2s+1)\theta)((1-e^{i\phi})b_0^2-1) = 0.$$

• Equivalently, since $b_0 = \sqrt{1 - g_0^2}$,

$$e^{i\tau}(1-e^{i\phi})g_0\sqrt{1-g_0^2}\sin((2s+1)\theta) = (1-(1-e^{i\phi})(1-g_0^2)\cos((2s+1)\theta).$$

The right-hand side equals (g₀²(1 - e^{iφ}) + e^{iφ}) cos ((2s + 1)θ).
So we want φ and τ to satisfy

$$\cot((2s+1)\theta) = \frac{e^{i\tau}(1-e^{i\phi})g_0\sqrt{1-g_0^2}}{g_0^2(1-e^{i\phi})+e^{i\phi}}$$

Approach 2: An Equation (Cont'd)

- Once ϕ is chosen, we choose τ to make the right-hand side real.
- To find ϕ , compute the magnitude squared of the right-hand side of the preceding equation

$$\frac{g_0^2 b_0^2 (2 - 2\cos\phi)}{g_0^4 (2 - 2\cos\phi) - g_0^2 (2 - 2\cos\phi) + 1}.$$

• The maximum value of the magnitude squared, obtained when $\cos \phi = -1$, is

$$\frac{4g_0^2b_0^2}{4g_0^4-4g_0^2+1}=\frac{4g_0^2b_0^2}{(2g_0^2-1)^2}$$

• So the maximum magnitude is

$$\frac{2g_0b_0}{2g_0^2-1} = \frac{2g_0b_0}{g_0^2-b_0^2} = \tan(2\theta),$$

where $\sin \theta = \sqrt{t} = g_0$ as before.

Approach 2: An Equation (Cont'd)

- We conclude that φ and τ can be chosen to make the right-hand side of the any real number between [0, tan (2θ)].
- By the geometric interpretation, after $s = \lfloor \frac{\pi}{4\theta} \frac{1}{2} \rfloor$ iterations, the state has been rotated to within 2θ of the desired state.
- We have shown that ϕ and τ can be chosen so that applying s iterations of Q, followed by one application of $Q(\phi, \tau)$, yields a solution with certainty.

Subsection 5

Unknown Number of Solutions

The Case of Unknown t

- Grover's algorithm requires that we know the relative number of solutions $t = \frac{|G|}{N}$ in order to determine how many times we should apply the transformation Q.
- More generally, amplitude amplification requires as input the success probability $t = |g_0|^2$ of $U|0\rangle$.
- We now sketch two approaches to handling cases in which we do not know *t*.
 - The first approach repeats Grover's algorithm multiple times, choosing a random number of iterations of Q in each run.
 - It succeeds in finding a solution with high probability.
 - The second approach, called **quantum counting**, uses the quantum Fourier transform to estimate *t*.
- Both approaches require $O(\sqrt{N})$ calls to U_P .

Varying the Number of Iterations

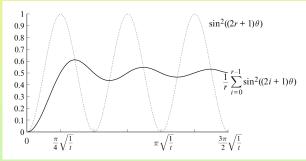
- Consider Grover's algorithm applied to a problem with *tN* solutions in a space of cardinality *N*.
- When t is unknown, a simple strategy is to repeatedly execute Grover's algorithm with a number of iteration steps picked randomly between 0 and $\frac{\pi}{4}\sqrt{N}$.
- For large values of t, this simple approach is clearly not optimal.
- Nevertheless, as we show, this simple strategy succeeds with at most $O(\sqrt{N})$ calls to U_P regardless of the value of t.
- Previous results imply that the average probability of success for a run with *i* iterations of *Q*, where *i* is randomly chosen between 0 and *r*, is given by

$$\Pr(i < r) = \frac{1}{r} \sum_{i=0}^{r-1} \sin^2((2i+1)\theta),$$

where $\sin \theta = \sqrt{t}$ as before.

Varying the Number of Iterations (Cont'd)

• A plot of the average success probability for different values of *r* is shown below.



- The graph will be identical for all values of t as long as $t \ll 1$.
- For comparison, the graph of the success probability after exactly *r* iteration steps of Grover's algorithm is also given.

Varying the Number of Iterations (Cont'd)

• It is easy to see from the graph that there is a constant c, such that

$$\Pr(i < r) > c$$
, for all $r \ge \frac{\pi}{4} \sqrt{\frac{1}{t}}$.

• Suppose $\frac{1}{t} \leq N$, guaranteeing at least one solution.

• Then, if we choose $r = \frac{\pi}{4}\sqrt{N}$, then

$$\Pr\left(i < \frac{\pi}{4}\sqrt{N}\right) \ge c.$$

- Thus, a single run of the algorithm, where the number of iterations of Q is chosen randomly between 0 and $\frac{\pi}{4}\sqrt{N}$, finds the solution with probability at least c.
- The expected number of calls to the oracle during such a run is therefore $O(\sqrt{N})$.

Varying the Number of Iterations (Cont'd)

- Take any probability c' > c.
- Then, there is a constant K, such that if Grover's algorithm is run K times, with the number of iterations for each run chosen as above, then a solution will be found with probability c'.
- Thus, for any c', the total number of times Q is applied is $O(\sqrt{N})$.
- Consequently, for any c', the total number of calls to the oracle is $O(\sqrt{N})$.

Quantum Counting

- Quantum counting takes a more quantum approach:
 - Create a superposition of results for different numbers of applications of *Q*;
 - Then use the quantum Fourier transform on that superposition to obtain a good estimate for the relative number of solutions *t*.
- The same strategy can be used for the amplitude amplification algorithm to estimate the success probability t of $U|0\rangle$.
- This approach also has query complexity $O(\sqrt{N})$.

- Let U and Q be as defined in the amplitude amplification algorithm.
- Define a transformation **RepeatQ**, with input |k⟩ and |ψ⟩, that performs k iterations of Q on |ψ⟩:

RepeatQ:
$$|k\rangle \otimes |\psi\rangle \rightarrow |k\rangle \otimes Q^{k}|\psi\rangle$$
.

- This transformation is more powerful than the classical ability to repeat *Q* because **RepeatQ** can be applied to a superposition.
- We apply RepeatQ to a superposition of all k < M = 2^m tensored with the state U|0> to obtain

$$\frac{1}{\sqrt{M}}\sum_{k=0}^{M-1}|k\rangle\otimes U|0\rangle\rightarrow \frac{1}{\sqrt{M}}\sum_{k=0}^{M-1}|k\rangle\otimes (g_k|\psi_G\rangle+b_k|\psi_B\rangle),$$

where we ignore for the moment how M was chosen.

- A measurement of the right register in the standard basis produces a state |x⟩ that is one of the following:
 - A good state (orthogonal to $|\psi_B\rangle$);
 - A bad state (orthogonal to $|\psi_G\rangle$).
- Thus, the state of the left register collapses to either of:

$$|\psi\rangle = C \sum_{k=0}^{M-1} b_k |k\rangle$$
 or $|\psi\rangle' = C' \sum_{k=0}^{M-1} g_k |k\rangle.$

- Let us suppose the former state $|\psi
 angle$ is obtained.
- A similar reasoning applies for the latter case.
- Since, by a previous section, $b_k = \cos((2k+1)\theta)$, we get

$$|\psi\rangle = C \sum_{k=0}^{M-1} \cos\left((2k+1)\theta\right)|k\rangle.$$

• Apply the quantum Fourier transform to this state to obtain

$$\mathcal{F}: C\sum_{k=0}^{M-1} b_k |k\rangle \to \sum_{j=0}^{M-1} B_j |j\rangle.$$

- We explained that, for a cosine function of period $\frac{\pi}{\theta}$, most of the amplitude is in those B_j that are close the single value $\frac{M\theta}{\pi}$.
- If we measure the state now, from the measured value $|j\rangle$ we obtain, with high probability, a good approximation of θ by taking $\theta = \frac{\pi j}{M}$.
- Thus, with high probability, the value $t = \sqrt{\sin \theta}$ is a good approximation for:
 - The ratio of solutions in the case of Grover's algorithm;
 - The success probability of $U|0\rangle$ in the case of amplitude amplification.

- There is, of course, one issue remaining.
- We do not know a priori a proper value for *M*.
- This problem can be addressed by repeating the algorithm for increasing *M* until a meaningful value for *j* is read.
- We know that $\theta = \frac{j}{M}\pi$.
- So, for a given θ :
 - We will likely read an integer value $j \sim \frac{\theta M}{\pi}$;
 - *j* will be measured as 0 with high probability when *M* is chosen too small for the given problem.